

City of Valdez

Legislation Text

File #: 23-0254, Version: 1

ITEM TITLE:

Report: Meals Hill 65% Design and Funding Update

SUBMITTED BY: Anne N. Duhamel, PRCS Office Manager

FISCAL NOTES:

Expenditure Required: N/A Unencumbered Balance: N/A

Funding Source: N/A

RECOMMENDATION:

Receive & File

SUMMARY STATEMENT:

Huddle will present to the Parks & Recreation Commission the Meals Hill 65% Design.

Nate Duval, Capital Facilities Director, will give an update on Meals Hill funding:

Initial funding for the Meals Hill Project (Approx. \$900K) came with the sales agreement with the Exon Valdes Oil Spill Trust (EVOS) managed by the Great Land Trust (GLT). This initial funding was approved for the masterplan development (approx. \$300k) and initial design for some elements of the masterplan and materials procurement (approx. \$600k). The EVOS/GLT funding had specific requirements limiting the scope of use. These funding limitations were not known at the time of application submission for an Economic Development Administration (EDA) grant.

The EDA grant was submitted assuming all design would be funded with EVOS/GLT funds. The EVOS/GLT funds are considered "Federal Funds" and cannot be used as a match for the Federal EDA grant. The City was awarded the EDA grant in the amount of \$2,532,734 with a required City match of \$633,184 (80/20 split).

Upon learning that EVOS funds were limited, after grant award, the City petitioned the EDA to utilize grant and matching funds to cover additional design and construction administration (CA) expenses. The request by the city was denied by the EDA on 4/18.

To construct the project, the City will need to secure funds for additional design and CA from another City source or through a direct contribution from the City outside the EDA matching funds.

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Director Duval will present the potential options and outcomes with the Council on May 3rd.

The Meals Hill Master Plan is located at the following web address:

https://www.valdezak.gov/DocumentCenter/View/9607/Meals-Hill-Master-Plan